

HPC Programming

Message Passing Interface (MPI) with Python

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Shared System: Why two C extensions

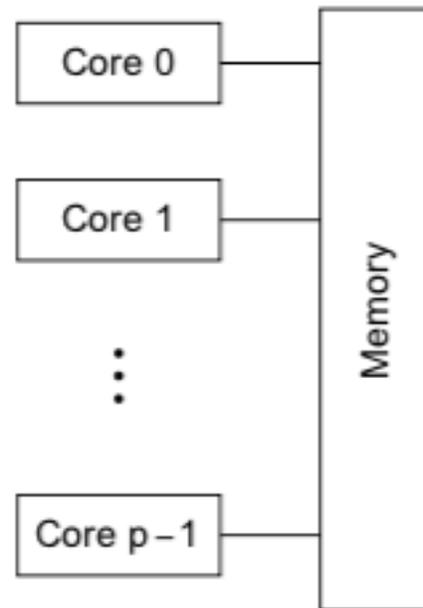
Recap

(a) Shared-Memory system:

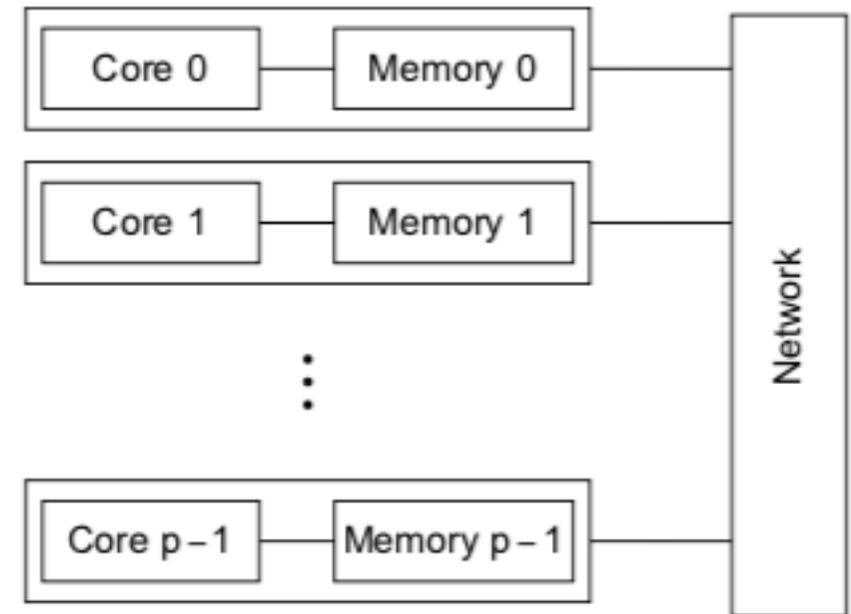
- Each core can read/write each memory location
- Coordination of cores via shared-memory locations
- Use OpenMP
- Small projects. HIMster2: up to 32 cores/node

(b) Distributed-Memory system:

- Each core has private memory
 - Cores explicitly sending messages for data exchange and coordination
 - MPI
 - Several nodes of a cluster
- Hybrid-Programming:
 - OpenMP+MPI



(a)



(b)

MPI: Getting Started (2)

Recap

„MPI = Sending and receiving messages“

rank 0



rank 1



Single Program, Multiple Data (SPMD)

Recap

- Standard MPI programming:
 - Write single executable
 - behaviour depends on its rank
 - eg rank=0: message collecting master, ranks>0: computing
 - Number of ranks from 1 to $O(10^4)$ on Himster2
 - $O(10^6)$ on extreme machines
 - called “Single Program, multiple Data”
- ⇔ Multiple-Program Multiple-Data (MPMD)
 - even mixture of different software possible with MPI: Fortran and C executable communicating fine

```
MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);  
  
if (my_rank == 0) {  
    ...  
} else {  
    ...  
}
```

MPI: Communicators

Recap

- MPI Communicator
= group of processes that can send messages to each other.

- All processes are in `MPI_COMM_WORLD` communicator

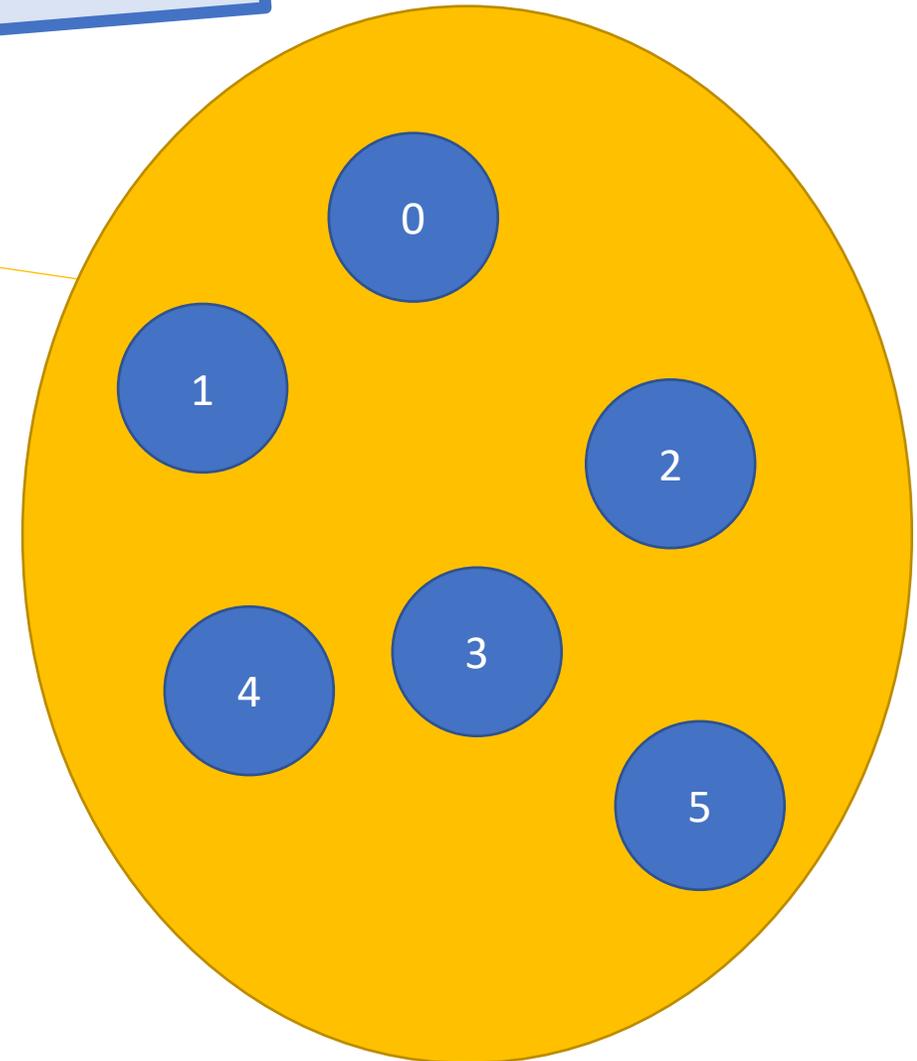
- Defining sub groups → see future lecture

- Number of members in communicator with

```
int MPI_Comm_size (  
    MPI_Comm comm    /*in*/,  
    int *comm_size_p /*out*/)
```

- Get rank of sub_process with

```
int MPI_Comm_rank (  
    MPI_Comm comm    /*in */,  
    int * my_rank_p  /*out*/)
```



MPI: Make a match

Recap

- rank s calls: `MPI_Send(send_buf, send_buf_size, send_type, dest, send_tag, send_comm);`
- rank q calls: `MPI_Recv(recv_buf, recv_buf_size, recv_type, src, recv_tag, recv_comm, &status);`
- All 5 “green” parameters need to match to get message successfully through.
 - all mandatory to be equal, except :
 - `recv_buf_size >= send_buf_size`
 - `dest = rank of receiving process, src = rank of sending process`

MPI: different communications modes

Recap

| | Blocking | Non-Blocking | note |
|------------------------------|-----------|--------------|--|
| standard send | MPI_Send | MPI_!Send | synchronous or asynchronous send (depending on message size and implementation) uses internal buffer. |
| synchronous send | MPI_SSend | MPI_!SSend | Only completes when the receive has started |
| asynchronous (buffered) send | MPI_BSend | MPI_!BSend | Completes after buffer copy (always). |
| ready send | MPI_RSend | MPI_!RSend | problematic: mandatory to have matching receive already listening. Not discussed in this lecture. Might be fastest solution. |

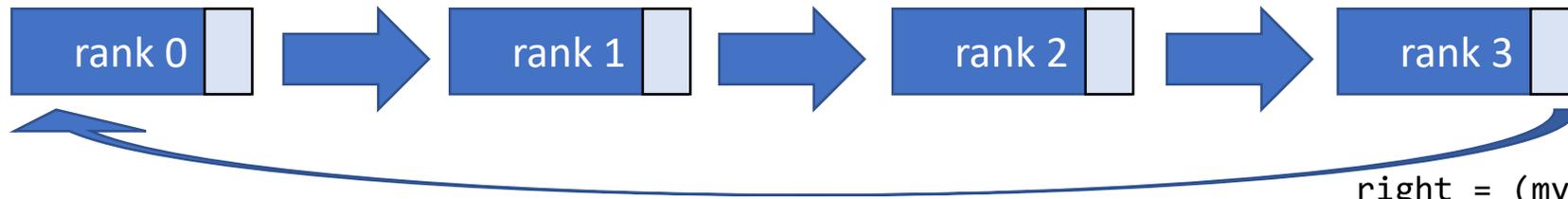
„i” stands for immediate return

| | Blocking | Non-Blocking | note |
|------------------|----------|--------------|---------------------------------|
| standard receive | MPI_Recv | MPI_IRecv | works for all sending routines. |

MPI: Non-Blocking Send & Receive

Recap

- to a 1D ring with 1 piece of data passing in one direction



```
right = (my_rank+1) % size;  
left = (my_rank-1+size) % size;
```

- **cyclic**: MPI_Send(...to right...)
MPI_Recv(...from left...)

deadlock!

All are waiting
for a receiver

- **non-cyclic**: for rank < size-2: MPI_Send(...to right...)
for rank > 0: MPI_Recv(...from left...)

serialisation!

highest rank starts,
rank 0 last

(hint: all this only true if MPI calls are synchronous sends)

MPI: Non-Blocking communication

Recap

This can be accomplished by:

- non-blocking send
 1. `MPI_Isend();`
 2. `Different_Work();`
 3. `MPI_Wait();` //Waits until `MPI_Isend` completed / send buffer is read out
- non-blocking receive
 1. `MPI_Irecv();`
 2. `Different_Work();`
 3. `MPI_Wait();` //Waits until `MPI_Irecv` completed / receive buffer is filled

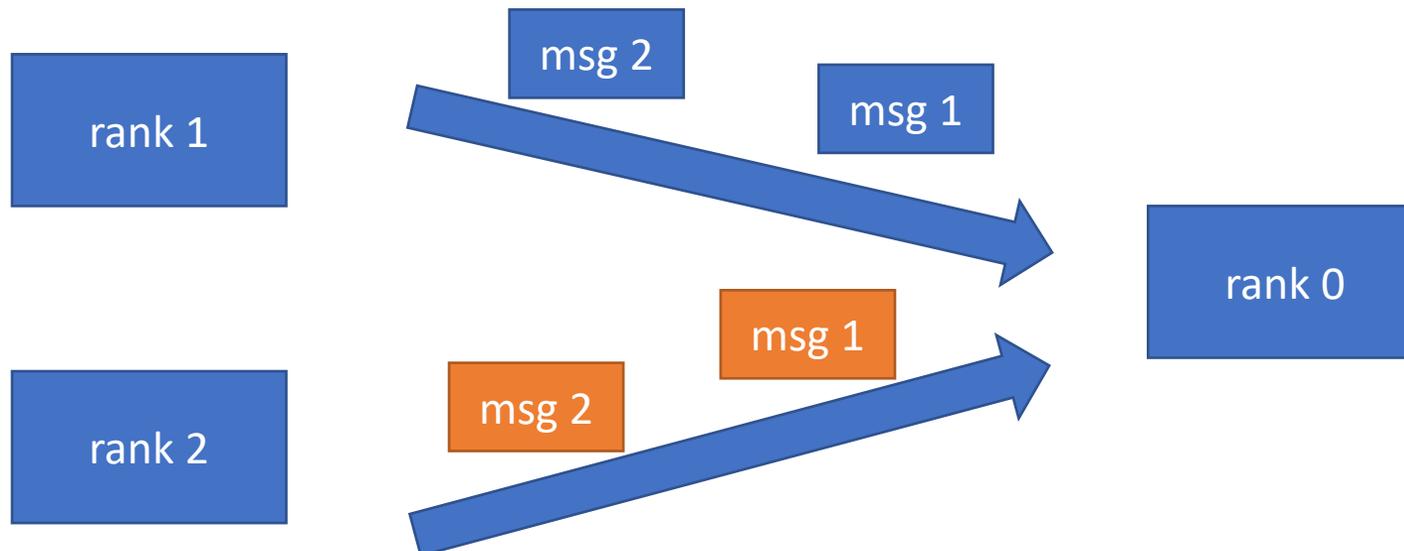
Golden MPI rule:
always ≤ 3 lines of
MPI_* calls per task

otherwise:
check MPI reference or
wrong coding

MPI: Message Order Preservation

Recap

- **Messages do not overtake**, if same:
 - communicator (eg MPI_COMM_WORLD),
 - source rank and
 - destination rank
- true for: synchronous and asynchronous communications
- messages from different senders can overtake



Introduction MPI4Py

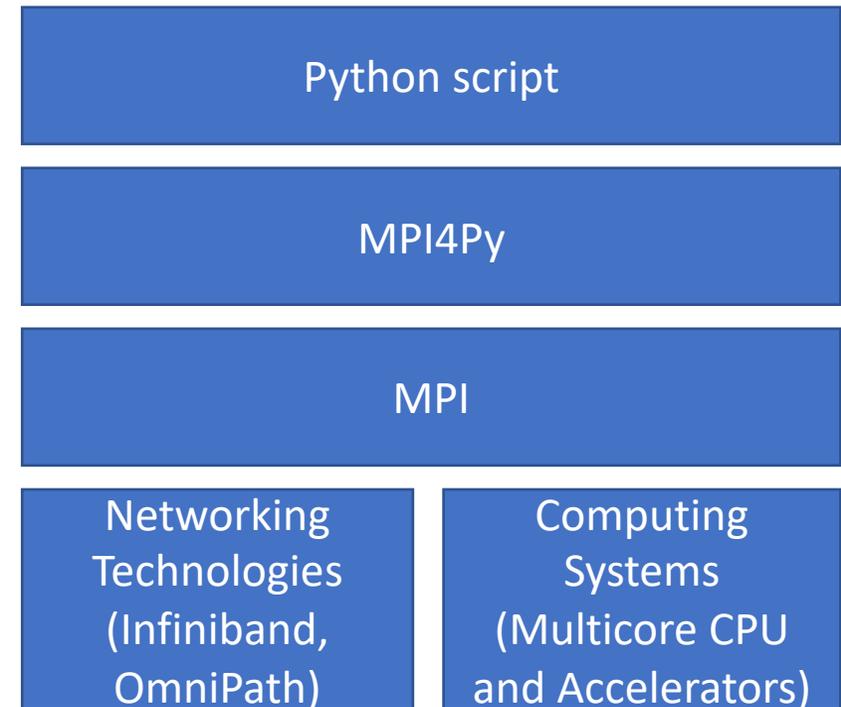


1. Overview / Getting Started
2. Messages & Point-to-point Communication
3. Nonblocking Communication
4. Collective Communication
5. Dealing with I/O
6. Groups & Communicators
7. MPI Derived Datatypes
8. Common pitfalls and good practice (“need for speed”)

What is MPI4Py?



- MPI4Py = Intermediate Layer, MPI-1/2 bindings for Python (“calls MPI C-functions”)
- Supported: MPI-1
 - Groups & Communicators,
 - Point-to-point Communication (send, recv, isend, irecv, wait),
 - Collective Communication (broadcast, scatter, gather, reduce, ...)
 - and features from MPI-2: MPI-IO, one-sided operations, ...
 - But no MPI-3
- multiple processes: no problem with Python Global Interpreter Lock (GIL)
- Written in cython (= “compiled python”)
- docs: <https://mpi4py.readthedocs.io>
- code: <https://github.com/mpi4py/mpi4py>
- lack of documentation: MPI standard and code mandatory



Gain information

- Recap the last MPI lectures on C, check the MPI-standard
- Search in <https://github.com/mpi4py/mpi4py> for function name
 - Note on github search:
„At most, search results can show two fragments from the same file, but there may be more results within the file.“
 - Most of the python communication functions today are defined in:
mpi4py/src/mpi4py/MPI/Comm.pyx
<https://github.com/mpi4py/mpi4py/blob/18c52a947443765dea0adaee0b702c044d9f150c/src/mpi4py/MPI/Comm.pyx>
 - Search for „def ssend(“

MPI: MPI.send

- Sending a message to another receiving rank

- Syntax:

```
def send(self, obj, int dest, int tag=0):  
    """Send"""  
    cdef MPI_Comm comm = self.ob_mpi  
    return PyMPI_send(obj, dest, tag, comm)
```

MPI: Elementary datatypes

- Python/NumPy/C types can't be passed
→ use MPI datatypes
- Advantage: interoperability with other software and hardware

| MPI Python datatype | C equivalent | NumPy |
|------------------------|------------------------|-------|
| MPI.SHORT | short int | h |
| MPI.INT | int | i |
| MPI.LONG | long int | l |
| MPI.LONG_LONG | long long int | q |
| MPI.UNSIGNED_CHAR | unsigned char | B |
| MPI.UNSIGNED_SHORT | unsigned short int | H |
| MPI.UNSIGNED_INT | unsigned int | I |
| MPI.UNSIGNED_LONG | unsigned long int | L |
| MPI.UNSIGNED_LONG_LONG | unsigned long long int | Q |
| MPI.FLOAT | float | f |
| MPI.DOUBLE | double | d |
| MPI.LONG_DOUBLE | long double | g |
| MPI.SIGNED_CHAR | char | b |
| MPI.C_DOUBLE_COMPLEX | | D |

Communication functions 1/2

- Can communicate any built-in or user-defined Python object (using pickle module)
- Transmission of python objects:
 - lowercase functions (send, recv, ...)
 - high level and convenient, but slow for large data
 - pickle serialisation:
 - object → pickle.dump() → MPI.send()
 - object ← pickle.load() ← MPI.recv()

Communication functions 2/2

- Supports direct communication of any object exporting the single-segment buffer interface.
- Transmission of array data (as binary data)
 - uppercase functions (Send, Recv, ...)
 - Fast, but low level and more verbose
 - message = [object memory, count, datatype]
 - communicate memory buffers
 - allocate send/receive buffer prior usage!!

Use considerations

- When to use:
 - existing python code: with multiple processes
 - benefit from python libraries (eg numpy)
- ... and not:
 - Memory intense programs, often used, core functionality → use C

Usage, Initialization, Exit, Timer

- module load lang/Python/3.6.6-foss-2018b
- Python code:

```
try:  
    from mpi4py import MPI  
except ImportError:  
    print("mpi4py module not loaded.")
```
- MPI initialization and finalization: `MPI.Init()`, `MPI.Finalize()`
- MPI module:
 - `MPI_Init()` is called on import
 - calls `MPI_Finalize()` just before the Python process terminates
- MPI timer: `MPI.Wtime()`, `MPI.Wtick()`

Usage: Communicators and Ranks

„Hello World“: import, create a *communicator* and get the *rank* :

```
from mpi4py import MPI
comm = MPI.COMM_WORLD
rank = comm.Get_rank()
print('My rank is ',rank)
```

- Save this to a file call comm.py and then run it:
mpirun -n 4 python filename.py

Usage: Point-to-Point Communication

With pickle / lowercase functions:

- Send any pickable object: dictionary, integer, string, user object...
- with lowercase functions

- Blocking:

```
comm.send(data, dest=1, tag=1)  
data = comm.recv(source=0, tag=1)
```

- Non-Blocking with isend:

```
req = comm.isend(data, dest=1, tag=1)  
req.wait()
```

- Non-Blocking with irecv:

```
req = comm.irecv(source=0, tag=1)  
data = req.wait()
```

Usage: Send numpy arrays (fast)

With capital function names (without pickle), for NumPy arrays:

- Blocking:

```
# automatic MPI datatype discovery
if rank == 0:
    data = numpy.arange(100, dtype=numpy.float64)
    comm.Send(data, dest=1, tag=13)
elif rank == 1:
    data = numpy.empty(100, dtype=numpy.float64)
    comm.Recv(data, source=0, tag=13)
```

Collective Communication

- `data = comm.bcast(data, root=0)`
- `comm.Scatter(data, recvbuf, root=0)`
- `comm.Gather(sendbuf, recvbuf, root=0)`
- `comm.Reduce(value, value_sum, op=MPI.SUM, root=0)`

MPI4Py exercises

- Setup your workspace:

<https://gitlab.rlp.net/pbotte/learnhpc/tree/master/mpi4py>

- Try out exercises 1-6

- Optional: advanced examples:

<https://github.com/jbornschein/mpi4py-examples>